

SPRING 2024 MATH 590: EXAM 2 SOLUTIONS

Name:

Throughout V will denote a vector space over $F = \mathbb{R}$ or \mathbb{C} , T a linear transformation from V to V and A a matrix with entries in $F = \mathbb{R}$ or \mathbb{C} .

(I) **True-False:** Write true or false next to each of the statements below. (3 points each)

- (a) Suppose A is a 4×4 real matrix whose columns are linearly independent. Then the rows of A are linearly independent. **True.** See the theorem from the Daily Update of February 28.
- (b) Suppose $v_1, v_2 \in \mathbb{R}^2$ are eigenvectors for a real, symmetric 2×2 matrix. Then v_1, v_2 are orthogonal. **False.** v_1 and v_2 could belong to the same eigenspace.
- (c) Let $\lambda \in \mathbb{R}$ be an eigenvalue of the matrix A . Then the geometric multiplicity of A is less than or equal to the algebraic multiplicity of A . **True.** The geometric multiplicity is always less than or equal to the algebraic multiplicity. See Fact due from the Daily Update of March 18.
- (d) Suppose P and A are 2×2 real matrices satisfying: $P^{-1} = P^t$ and $P^{-1}AP = D$, where D is a diagonal matrix. Then A is a symmetric matrix. **True.** From $P^tAP = D$, one gets $P^tA^tP = (P^tAP)^t = D^t = D = P^tAP$. Cancelling P^t and P gives $A^t = A$.
- (e) Suppose $T : \mathbb{R}^4 \rightarrow \mathbb{R}^4$ is a symmetric linear transformation and $\alpha \subseteq \mathbb{R}^4$ is a basis. Then $[T]_\alpha^\alpha$ is a symmetric matrix. **False.** α must be an orthonormal basis.

(II) **State the indicated definition, proposition or theorem.** (5 points each)

(a) Suppose $\lambda \in F$ is an eigenvalue of $T : V \rightarrow V$. Define the *geometric multiplicity* and the *algebraic multiplicity* of T .

Solution. Suppose $p_T(x) = (x - \lambda)^e q(x)$, with $q(\lambda) \neq 0$. Then e is the algebraic multiplicity of λ and $\dim(E_\lambda)$ is the geometric multiplicity of λ .

(b) State the theorem characterizing when an $n \times n$ matrix A with entries in F is diagonalizable.

Solution. For an $n \times n$ matrix A , the following are equivalent:

- (i) A is diagonalizable.
- (ii) $p_A(x) = (x - \lambda_1)^{e_1} \cdots (x - \lambda_r)^{e_r}$ and $\dim(E_{\lambda_i}) = e_i$, for $1 \leq i \leq r$.
- (iii) $p_A(x) = (x - \lambda_1)^{e_1} \cdots (x - \lambda_r)^{e_r}$ and $\dim(E_{\lambda_1}) + \cdots + \dim(E_{\lambda_r}) = n$.

(c) State the theorem about eigenvectors associated to distinct eigenvalues.

Solution. Let $T : V \rightarrow V$ be a linear transformation with distinct eigenvalues $\lambda_1, \dots, \lambda_r$. If $v_1, \dots, v_r \in V$ are eigenvectors with $T(v_i) = \lambda_i v_i$, for $1 \leq i \leq r$, then v_1, \dots, v_r are linearly independent.

(III) **Short Answer.** (15 points each)

(a) Give an example of a 3×3 matrix that has its eigenvalues in \mathbb{R} , but is **not** diagonalizable. You must justify your answer.

Solution. There are infinitely many matrices that satisfy these conditions. Take $A = \begin{pmatrix} 1 & 1 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix}$. Then

$p_A(x) = (x-1)^3$, so A has its eigenvalues in \mathbb{R} . Moreover 1 is an eigenvalue with algebraic multiplicity equal to three.

On the other hand, E_1 is the nullspace of $\begin{pmatrix} 0 & 1 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix}$, which has rank one. Therefore its nullspace has dimension two, i.e., $\dim(E_1) = 2 < 3$, so A is not diagonalizable.

(b) Suppose $A = \begin{pmatrix} 1 & 1 & 1 & 1 & 1 \\ 1 & 1 & 1 & 1 & 1 \\ 1 & 1 & 1 & 1 & 1 \\ 1 & 1 & 1 & 1 & 1 \\ 1 & 1 & 1 & 1 & 1 \end{pmatrix}$. Give a detailed explanation why A is diagonalizable. Note, we have

$p_A(x) = x^4(x-5)$.

Solution. The eigenvalues of A are 0, with algebraic multiplicity four, and 5 with algebraic multiplicity one.

E_0 is the nullspace of $\begin{pmatrix} 1 & 1 & 1 & 1 & 1 \\ 1 & 1 & 1 & 1 & 1 \\ 1 & 1 & 1 & 1 & 1 \\ 1 & 1 & 1 & 1 & 1 \\ 1 & 1 & 1 & 1 & 1 \end{pmatrix} \xrightarrow{\text{EROs}} \begin{pmatrix} 1 & 1 & 1 & 1 & 1 \\ 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 \end{pmatrix}$, which has rank one. Thus, the nullspace of E_0 has dimension four, which equals the algebraic multiplicity of 0.

On the other hand the algebraic multiplicity of 1 equals one, which forces the geometric multiplicity to be one, since the latter is less than or equal to the former. Therefore, A is diagonalizable.

(c) Suppose V is the vector space spanned by the matrices $v_1 = \begin{pmatrix} 0 & -1 \\ -1 & 0 \end{pmatrix}$, $v_2 = \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix}$, $v_3 = \begin{pmatrix} 1 & 1 \\ 1 & 1 \end{pmatrix}$ over \mathbb{R} with inner product $\langle A, B \rangle := \text{trace}(A^t B)$. Find an orthogonal basis for V .

Solution. We apply the Gram Schmidt process to v_1, v_2, v_3 . Set $w_1 = v_1$. Then, $w_2 = v_2 - \frac{\langle v_2, w_1 \rangle}{\langle w_1, w_1 \rangle} w_1$. We have

$$\langle v_2, w_1 \rangle = \text{trace} \left\{ \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix} \cdot \begin{pmatrix} 0 & -1 \\ -1 & 0 \end{pmatrix} \right\} = \text{trace} \begin{pmatrix} 0 & -1 \\ 1 & 0 \end{pmatrix} = 0,$$

so that $w_2 = v_2$.

$$w_3 = v_3 - \frac{\langle v_3, w_1 \rangle}{\langle w_1, w_1 \rangle} w_1 - \frac{\langle v_3, w_2 \rangle}{\langle w_2, w_2 \rangle} w_2.$$

We have

$$\begin{aligned}\langle v_3, w_1 \rangle &= \text{trace} \left\{ \begin{pmatrix} 1 & 1 \\ 1 & 1 \end{pmatrix} \cdot \begin{pmatrix} 0 & -1 \\ -1 & 0 \end{pmatrix} \right\} = \text{trace} \begin{pmatrix} -1 & -1 \\ -1 & -1 \end{pmatrix} = -2 \\ \langle w_1, w_1 \rangle &= \text{trace} \left\{ \begin{pmatrix} 0 & -1 \\ -1 & 0 \end{pmatrix} \cdot \begin{pmatrix} 0 & -1 \\ -1 & 0 \end{pmatrix} \right\} = \text{trace} \begin{pmatrix} 1 & 1 \\ 0 & 1 \end{pmatrix} = 2 \\ \langle v_3, w_2 \rangle &= \text{trace} \left\{ \begin{pmatrix} 1 & 1 \\ 1 & 1 \end{pmatrix} \cdot \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix} \right\} = \text{trace} \begin{pmatrix} 1 & -1 \\ 1 & -1 \end{pmatrix} = 0\end{aligned}$$

Therefore,

$$w_3 = v_3 - \frac{-2}{2}w_1 = \begin{pmatrix} 1 & 1 \\ 1 & 1 \end{pmatrix} + \begin{pmatrix} 0 & -1 \\ -1 & 0 \end{pmatrix} = \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix}.$$

We now have an orthogonal basis for V , namely w_1, w_2, w_3 .

(IV) **Proof Problem.** Suppose A is a 7×7 matrix with entries in \mathbb{R} with characteristic polynomial $p_A(x) = (x - \lambda_1)^2(x - \lambda_2)^3(x - \lambda_3)^2$ and $\dim(E_{\lambda_1}) = 2, \dim(E_{\lambda_2}) = 3, \dim(E_{\lambda_3}) = 2$. Give a **direct proof** that A is diagonalizable and identify a matrix P such that $P^{-1}AP$ is a diagonal matrix. Note, by a direct proof we mean one cannot use the theorem characterizing diagonalizability. (25 points)

Solution. Viewing \mathbb{R}^7 as the space of column vectors, let u_1, u_2 be a basis for E_{λ_1} , v_1, v_2, v_3 be a basis for E_{λ_2} , and w_1, w_2 be a basis for E_{λ_3} . Set $P = [u_1 \ u_2 \ v_1 \ v_2 \ v_3 \ w_1 \ w_2]$. From the definition of P , we have

$$\begin{aligned}AP &= [Au_1 \ Au_2 \ Av_1 \ Av_2 \ Av_3 \ Aw_1 \ Aw_2] \\ &= [\lambda_1 u_1 \ \lambda_1 u_2 \ \lambda_2 v_1 \ \lambda_2 v_2 \ \lambda_2 v_3 \ \lambda_3 w_1 \ \lambda_3 w_2] \\ &= PD,\end{aligned}$$

where D is the 7×7 diagonal matrix with diagonal entries $\lambda_1, \lambda_1, \lambda_2, \lambda_2, \lambda_2, \lambda_3, \lambda_3$. Once we show that $u_1, u_2, v_1, v_2, v_3, w_1, w_2$ is a basis for \mathbb{R}^7 , then P is an invertible matrix. Thus, from $AP = PD$, we get $P^{-1}AP = D$, showing that A is diagonalizable. But seven linearly independent vectors in \mathbb{R}^7 form a basis for \mathbb{R}^7 , so we just have to show that the columns of P are linearly independent.

Suppose

$$\alpha_1 u_1 + \alpha_2 u_2 + \beta_1 v_1 + \beta_2 v_2 + \beta_3 v_3 + \gamma_1 w_1 + \gamma_2 w_2 = \vec{0}.$$

If we set $A := \alpha_1 u_1 + \alpha_2 u_2$, $B := \beta_1 v_1 + \beta_2 v_2 + \beta_3 v_3$, and $C := \gamma_1 w_1 + \gamma_2 w_2$, then $A \in E_{\lambda_1}, B \in E_{\lambda_2}, C \in E_{\lambda_3}$. We also have

$$1 \cdot A + 1 \cdot B + 1 \cdot C = \vec{0}.$$

Since eigenvectors corresponding to distinct eigenvalues are linearly independent, it follows that we must have $A = \vec{0}, B = \vec{0}, C = \vec{0}$. But v_1, v_2 are linearly independent, so $A = \vec{0}$ implies $\alpha_1 = \alpha_2 = 0$. Similarly, v_1, v_2, v_3 are linearly independent, so we have $\beta_1 = \beta_2 = \beta_3 = 0$, and likewise, $\gamma_1 = \gamma_2 = 0$, which shows that $u_1, u_2, v_1, v_2, v_3, w_1, w_2$ are linearly independent.

Bonus Problems. For ten bonus points, solve **one, and only one**, of the following bonus problems. In order to receive any bonus points, your answer must be completely (or, very close to completely) correct.

1. Suppose $T : \mathbb{R}^2 \rightarrow \mathbb{R}^2$ is a symmetric linear transformation. Prove that $[T]_\alpha^\alpha$ is a symmetric matrix, for every orthonormal basis $\alpha \subseteq \mathbb{R}^2$. Give an example where this fails, if α is not an orthonormal basis.

Solution. Suppose $T : \mathbb{R}^2 \rightarrow \mathbb{R}^2$ is a symmetric linear transformation. Prove that $[T]_\alpha^\alpha$ is a symmetric matrix, for every orthonormal basis $\alpha \subseteq \mathbb{R}^2$. Give an example where this fails, if α is not an orthonormal basis.

Solution. Suppose $\alpha = \{u_1, u_2\}$ is an orthonormal basis for \mathbb{R}^2 and $T(u_1) = au_1 + bu_2$, $T(u_2) = cu_1 + du_2$. It follows that $[T]_\alpha^\alpha = \begin{pmatrix} a & c \\ b & d \end{pmatrix}$.

We also have

$$T(u_1) \cdot u_2 = (au_1 + bu_2) \cdot u_2 = a(u_1 \cdot u_2) + b(u_2 \cdot u_2) = a \cdot 0 + b \cdot 1 = b,$$

and moreover,

$$u_1 \cdot T(u_2) = u_1 \cdot (cu_1 + du_2) = c(u_1 \cdot u_1) + d(u_1 \cdot u_2) = c \cdot 1 + d \cdot 0 = c.$$

Since $T(u_1) \cdot u_2 = u_1 \cdot T(u_2)$, it follows that $b = c$, showing that $[T]_\alpha^\alpha$ is symmetric.

Now consider $T(x, y) = (x + 2y, 2x + y)$, a symmetric linear transformation. If we let $v_1 = (1, 1)$ and $v_2 = (1, 0)$, then $\beta = \{v_1, v_2\}$ is a basis for \mathbb{R}^2 (since the corresponding determinant is not zero). On the other hand, $T(v_1) = (3, 3) = 3 \cdot v_1 + 0 \cdot v_2$ and $T(v_2) = (1, 2) = 2 \cdot v_1 - 1 \cdot v_2$, so that $[T]_\beta^\beta = \begin{pmatrix} 3 & 2 \\ 0 & -1 \end{pmatrix}$, which is not a symmetric matrix.

2. An important fact in linear algebra is the following: Suppose A and B are $n \times n$ diagonalizable matrices. If $AB = BA$, then A and B are *simultaneously diagonalizable*, i.e., there exists an invertible $n \times n$ matrix P such that $P^{-1}AP$ and $P^{-1}BP$ are diagonal matrices. For the matrices $A = \begin{pmatrix} 2 & 1 \\ 1 & 2 \end{pmatrix}$ and $B = \begin{pmatrix} 3 & 4 \\ 4 & 3 \end{pmatrix}$, verify that $AB = BA$ and find a 2×2 invertible matrix P such that P simultaneously diagonalizes both A and B .

Solution. $AB = \begin{pmatrix} 10 & 11 \\ 11 & 10 \end{pmatrix} = BA$. Moreover, $p_A(x) = (x - 1)(x - 3)$ and $p_B(x) = (x + 1)(x - 7)$.

For A , we have E_1 is the null space of $\begin{pmatrix} 1 & 1 \\ 1 & 1 \end{pmatrix}$ which has basis $\begin{pmatrix} 1 \\ -1 \end{pmatrix}$, while E_3 is the null space of $\begin{pmatrix} -1 & 1 \\ 1 & -1 \end{pmatrix}$ which has basis $\begin{pmatrix} 1 \\ 1 \end{pmatrix}$. Thus, for $P = \begin{pmatrix} 1 & 1 \\ -1 & 1 \end{pmatrix}$, we have $P^{-1}AP = \begin{pmatrix} 1 & 0 \\ 0 & 3 \end{pmatrix}$.

For B , we have E_{-1} is the null space of $\begin{pmatrix} 4 & 4 \\ 4 & 4 \end{pmatrix}$, which has basis $\begin{pmatrix} 1 \\ -1 \end{pmatrix}$ and E_7 is the null space of $\begin{pmatrix} -4 & 4 \\ 4 & -4 \end{pmatrix}$ which has basis $\begin{pmatrix} 1 \\ 1 \end{pmatrix}$, thus, for $P = \begin{pmatrix} 1 & 1 \\ -1 & 1 \end{pmatrix}$, we have $P^{-1}BP = \begin{pmatrix} -1 & 0 \\ 0 & 7 \end{pmatrix}$, which shows that P diagonalizes both A and B .